

Geant4 ML-based laser-plasma sources term implementation in the context of the PALLAS beamline design

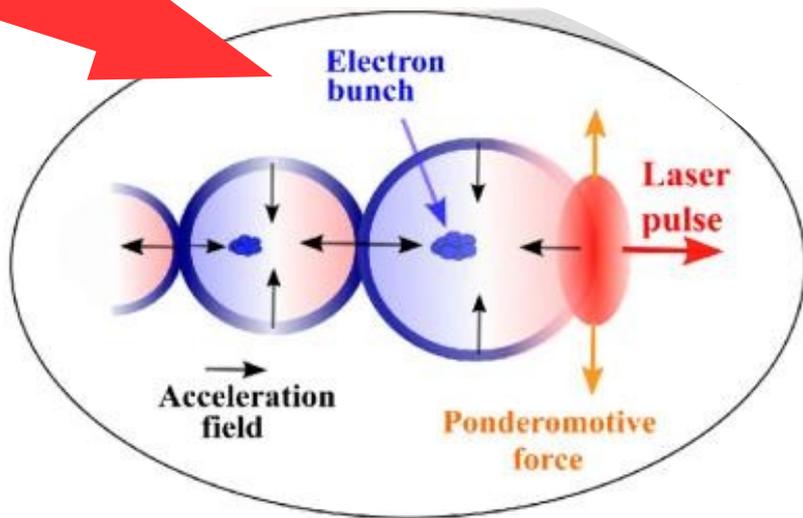
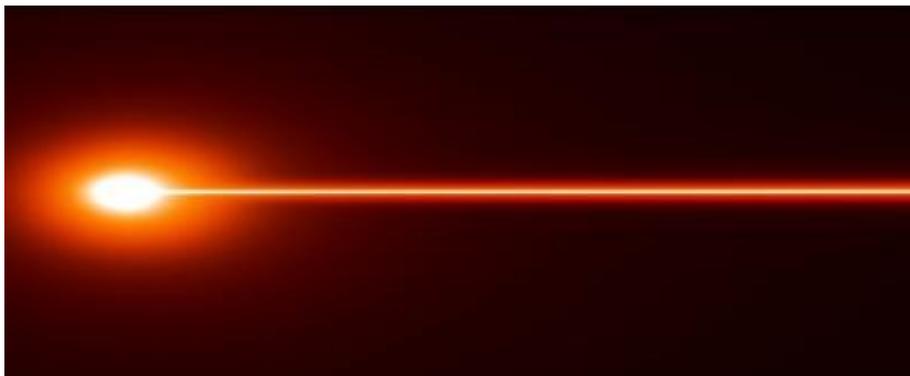
K. Cassou, A. Huber, V. Kubytskyi,
M. Lenivenko, A. Sytov



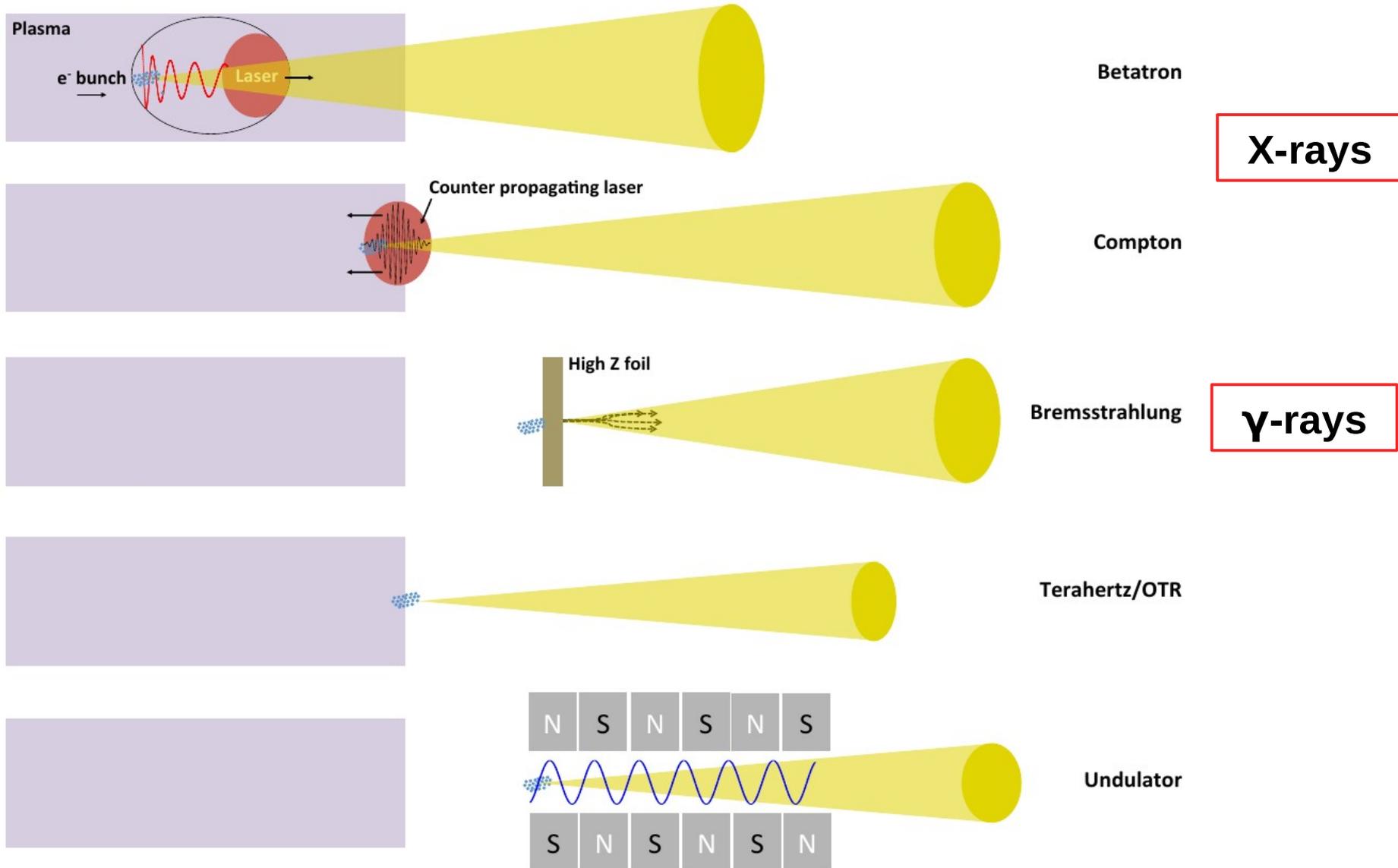
Laser plasma wakefield acceleration (LWFA)



Electron beam energy:
MeV — tens of **GeV**

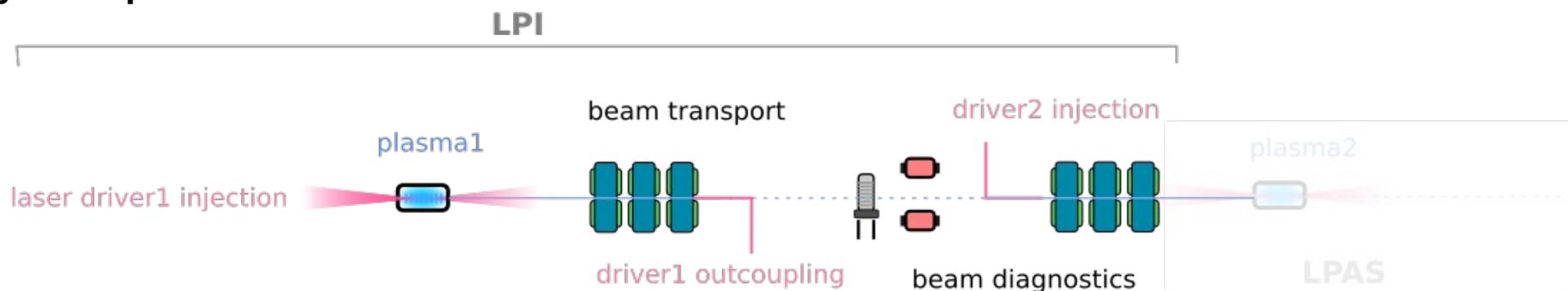


Radiation source based on plasma acceleration of electrons



Test facility for laser-plasma injector optimisation towards RF control reliability

In the context of advanced accelerator high quality beam laser plasma injector (LPI) for **EuPRAXIA** [1] preparatory technical design phase and future high gradient accelerator R&D at IJClab [2]: 10 Hz 250MeV LPI test facility to improve **quality and stability of e- beam generated by laser-plasma accelerator**.



Plasma target development [3]

- testing various gas cell type
- Continuous flow
- In-lin integration

Beam Transport [4]

- compact flexible capture
- active plasma lens capture test
- collimator system for energy selection

e- beam compact characterization

- down to 500 keV energy
- resolution emittance
- longitudinal phase space

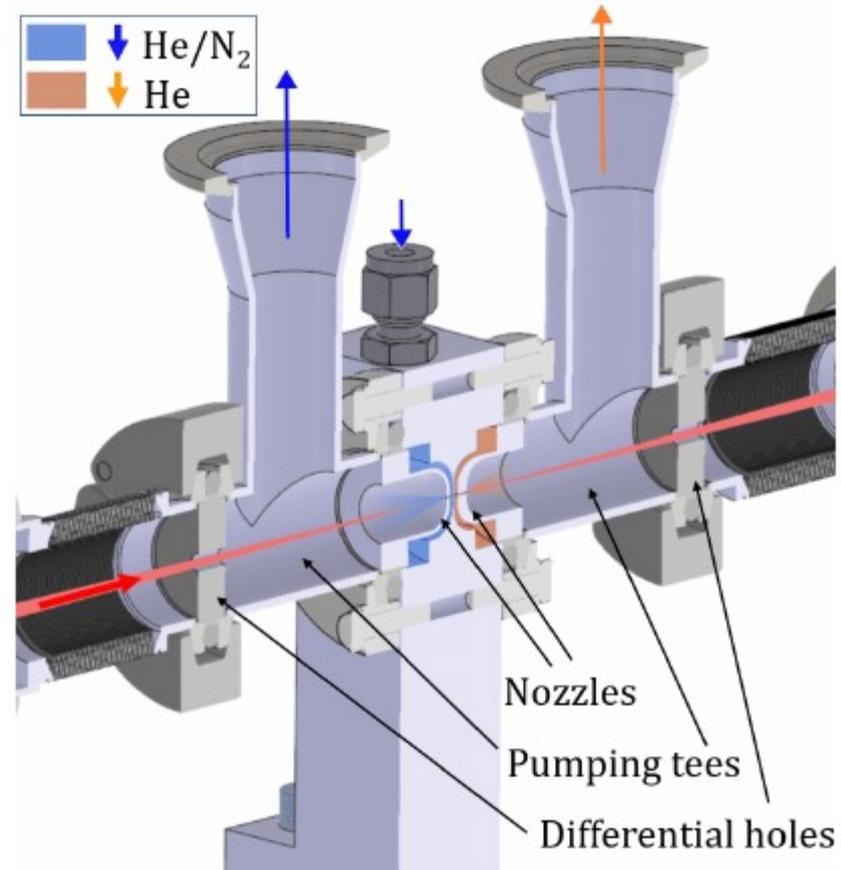
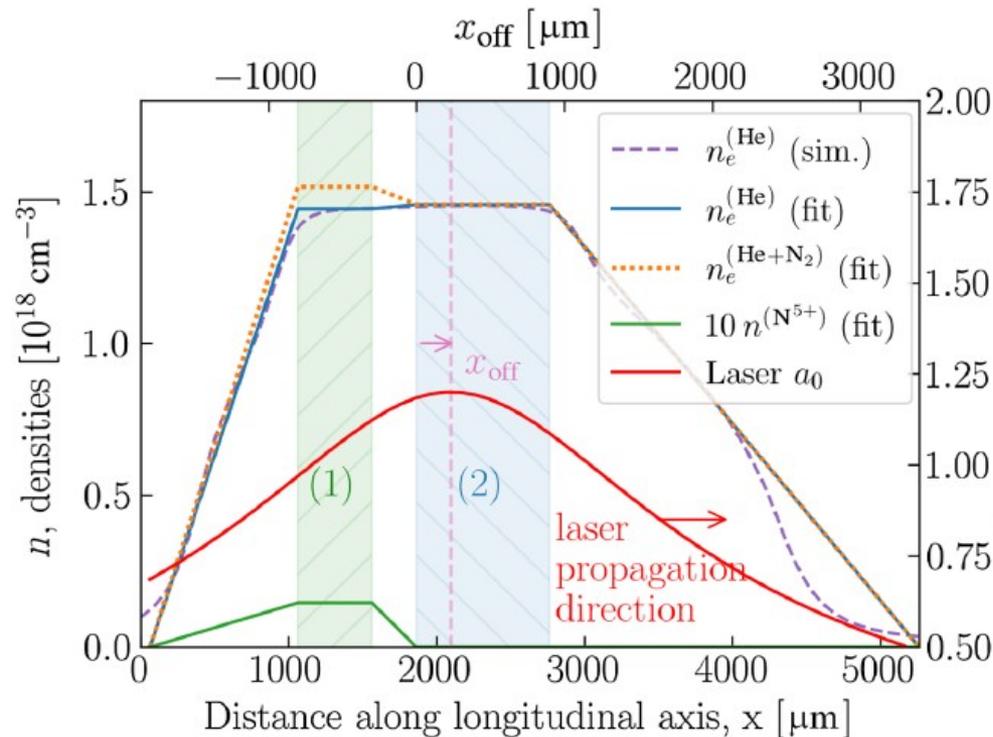
[1] Assmann, R. W. et al. EuPRAXIA Conceptual Design Report. Eur. Phys. J. Spec. Top. 229, 3675–4284 (2020).

[2] pallas.ijclab.in2p3.fr

[3] Drobniak, P. et al. Random scan optimization of a laser-plasma electron injector based on fast particle-in-cell simulations. Phys. Rev. Accel. Beams 26, 091302 (2023), Drobniak, P. et al. Two-chamber gas target for laser-plasma accelerator electron source. Preprint at <http://arxiv.org/abs/2309.11921> (2023).

[4] C. Guyot et al. Benchmarking CODAL beam dynamics code: a laser plasma case study, IPAC 2023 WEPL084

Gas density profile generated using **OpenFOAM** code



First chamber (with N₂ gas dopant) is used for injection, while the second one (pure He) for acceleration

PHYSICAL REVIEW ACCELERATORS AND BEAMS **26**, 091302 (2023)

Random scan optimization of a laser-plasma electron injector based on fast particle-in-cell simulations

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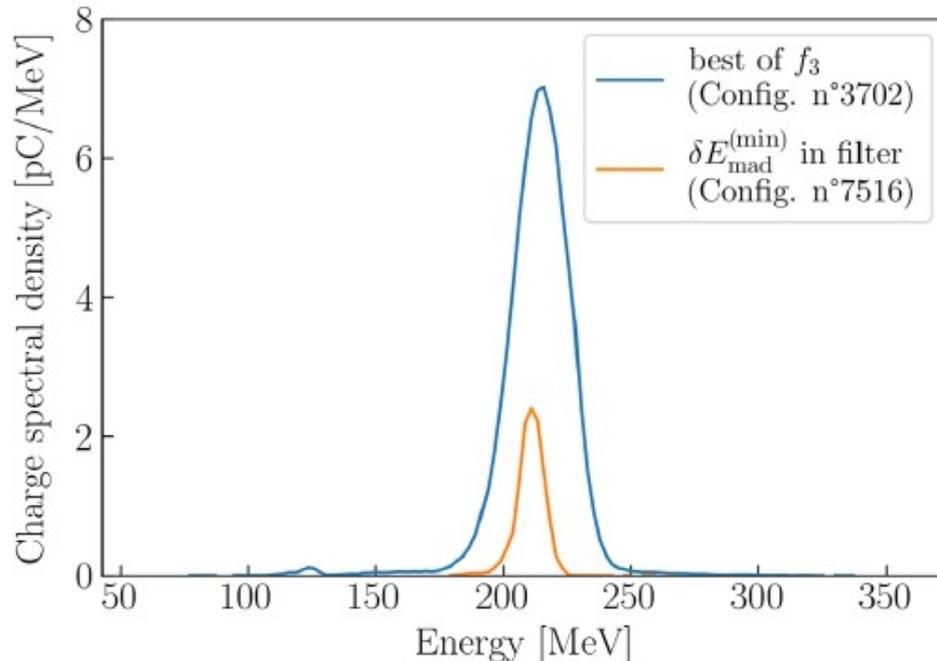


TABLE II. Input and beam parameters of LPI configurations 3702 and 7516.

| | Best of f_3 | $\delta E_{\text{mad}}^{(\text{min})}$ in filter |
|------------------------------------|---------------|--|
| N° | 3702 | 7516 |
| Origin | RS2 | RS4 |
| p (mbar) | 58.6 | 47.8 |
| $a_{0,\text{vac,max}}$ | 1.43 | 1.23 |
| x_{off} (μm) | 558 | 1680 |
| c_{N_2} (%) | 1.88 | 6.17 |
| $a_{0,\text{eff,max}}$ | 3.73 | 2.58 |
| Q (pC) | 198 | 30 |
| E_{med} (MeV) | 215 | 212 |
| δE_{mad} (%) | 3.53 | 1.55 |
| $\epsilon_{y,n}$ (μm) | 5.03 | 1.74 |

PIC simulations with **SMILEI**

A modeling of the **full beamline** using **Geant4** is required for collimator design

Dataset and **first ML** model generated by **PALLAS**

Key idea:
ML model into Geant4 to create a **Geant4 electron beam source** based on plasma acceleration

```
#ifndef B1PrimaryGeneratorAction_h
#define B1PrimaryGeneratorAction_h 1

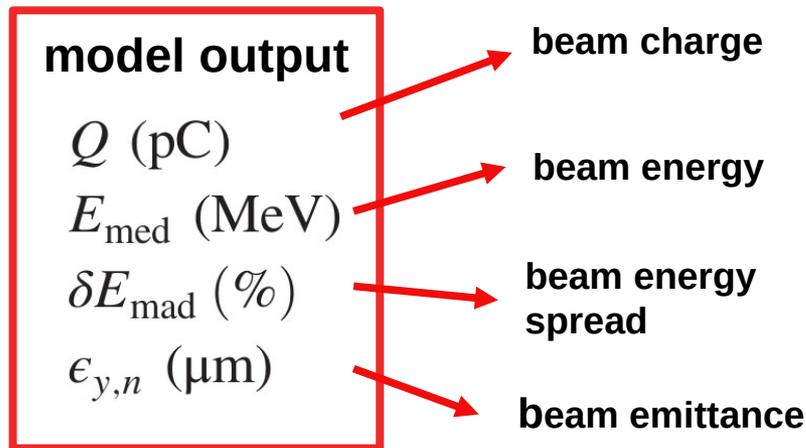
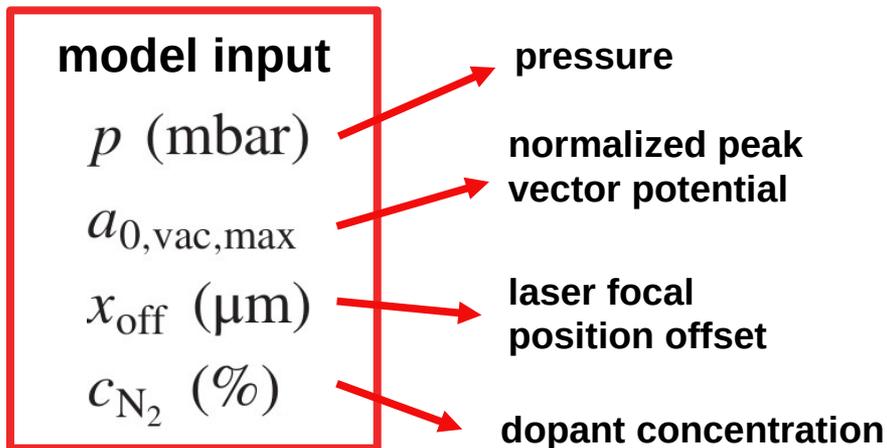
#include "G4VUserPrimaryGeneratorAction.hh"
#include "globals.hh"
#include "G4GeneralParticleSource.hh"
#include "G4ParticleGun.hh"
#include <memory>
#include <onnxruntime_c_api.h>
#include <onnxruntime_cxx_api.h>
class G4ParticleGun;
class G4Event;
```

```
PrimaryGeneratorAction::PrimaryGeneratorAction(): G4VUserPrimaryGeneratorAction(),
    fParticleGun(0),
    fEnvelopeBox(0)
{
    G4int n_particle = 1;
    fParticleGun = new G4ParticleGun(n_particle);

    // default particle kinematic
    fParticleGun->SetParticleDefinition(
        G4ParticleTable::GetParticleTable()->FindParticle("e-"));

    //Neural network: create onnx session
    Ort::Env env(ORT_LOGGING_LEVEL_WARNING, "plasma");
    Ort::SessionOptions session_options;
    session_options.SetIntraOpNumThreads(1);
    auto sessionLocal =
        std::make_unique<Ort::Session>(env, "model2.onnx", session_options);
    fSession = std::move(sessionLocal);

    // Get input node information
    fMemory_info = Ort::MemoryInfo::CreateCpu(
        OrtAllocatorType::OrtArenaAllocator, OrtMemTypeDefault);
```



| Layer (type) | Output Shape | Param # |
|---------------------|--------------|---------|
| dense (Dense) | (None, 50) | 250 |
| p_re_lu (PReLU) | (None, 50) | 50 |
| dropout (Dropout) | (None, 50) | 0 |
| dense_1 (Dense) | (None, 50) | 2,550 |
| p_re_lu_1 (PReLU) | (None, 50) | 50 |
| dropout_1 (Dropout) | (None, 50) | 0 |
| dense_2 (Dense) | (None, 50) | 2,550 |
| p_re_lu_2 (PReLU) | (None, 50) | 50 |
| dropout_2 (Dropout) | (None, 50) | 0 |
| dense_3 (Dense) | (None, 4) | 204 |

Model: "sequential"

Total params: 9,092 (35.52 KB)

Trainable params: 9,092 (35.52 KB)

Non-trainable params: 0 (0.00 B)

```
##### Calling the dataframe and preparing the data #####
root_df = './'
root_models = './'

df01=pd.read_pickle("D:/B001_dataframe_surrogateopt_randscan.pickle")

# Deleting no injection configurations
df01['dE_mad'] = df01['dE_mad'].replace([0], np.nan)
df01 = df01[df01['dE_mad'].notna()]

# Choose needed columns (if take all columns scaler will have an error as some columns not numeric)
df01 = df01[["x_of", "a_0", "c_N2", "p_1", "E_med", "dE_mad", "q_end", "n_emit_y"]]
df = df01.copy()

print(len(df))

min_values = df.min()
print("Minimum values:\n", min_values)

max_values = df.max()
print("Maximum values:\n", max_values)

print(repr(df))
```

Model from large &
fast PIC simulations

```
Minimum values:
  x_of      -3.998247e+02
  a_0       1.100516e+00
  c_N2      2.064164e-03
  p_1       1.009451e+01
  E_med     5.849625e+01
  dE_mad    8.269990e-04
  q_end     6.498496e-17
  n_emit_y  2.504754e-09
dtype: float64
Maximum values:
  x_of      1.798325e+03
  a_0       1.849792e+00
  c_N2      1.199827e-01
  p_1       9.995741e+01
  E_med     7.252073e+02
  dE_mad    7.512749e-01
  q_end     9.688866e-10
  n_emit_y  8.082236e-05
dtype: float64
```

Rescaling

```
# Data rescaling
scaler = MinMaxScaler() #MinMax works very good if borders of inputs in different data sets at least close to each other
df_transformed = scaler.fit_transform(df)
df = pd.DataFrame(df_transformed,
                  columns=df.columns.values.tolist())

min_values = df.min()
print("Minimum values:\n", min_values)

max_values = df.max()
print("Maximum values:\n", max_values)

print(repr(df))
```

```
Minimum values:
  x_of      0.0
  a_0       0.0
  c_N2      0.0
  p_1       0.0
  E_med     0.0
  dE_mad    0.0
  q_end     0.0
  n_emit_y  0.0
dtype: float64
Maximum values:
  x_of      1.0
  a_0       1.0
  c_N2      1.0
  p_1       1.0
  E_med     1.0
  dE_mad    1.0
  q_end     1.0
  n_emit_y  1.0
dtype: float64
```

Entrée [51]: `# our test set`
`x_test.to_numpy()`

Out[51]: `array([[0.04414279, 0.03696395, 0.14718525, 0.92301997]`
`[0.98181373, 0.37218034, 0.6189666 , 0.19693942]`
`[0.2311267 , 0.1554619 , 0.53956506, 0.61822893]`
`...]`
`[0.90003744, 0.62109482, 0.49487012, 0.0943088]`,
`[0.70989143, 0.06717811, 0.68066123, 0.97240594]`,
`[0.73405388, 0.32554836, 0.07308455, 0.57993409]])`

**Model on python
with ONNX**

Entrée [53]: `#predict the same with onnx model`
`#you need to rerun entire notebook to get the same results as for keras`
`input_data=x_test.to_numpy()`
`session.run(None, {input_name: input_data})`

Out[53]: `[array([[1.3585013e-01, 6.1869740e-01, 2.1406868e-01, 2.4686235e-01],`
`[4.1216230e-01, 1.4092088e-02, 8.6262226e-03, 7.2836876e-05],`
`[1.5716442e-01, 4.8624346e-01, 3.1221294e-01, 2.3242965e-01],`
`...]`
`[3.6191791e-01, 1.4332026e-02, 8.8895857e-03, 3.8057566e-05],`
`[9.0673089e-02, 6.6863406e-01, 2.7304298e-01, 5.6681705e-01],`
`[6.4218014e-01, 5.3200334e-02, 9.9563301e-02, 7.5561881e-02]])`
`dtype=float32]`

**Model on G4
with ONNX**

```
Output tensor values:
0.13585 0.618697 0.214069 0.246862
0.412162 0.0140921 0.00862622 7.28369e-05
0.157164 0.486243 0.312213 0.23243
```

Correspondence OK

```

G4double fXof_min = -399.8247;
G4double fXof_max = 1798.325;
G4double fXof_rescaled = fXof / (fXof_max - fXof_min) - fXof_min/(fXof_max - fXof_min);

G4double fA0_min = 1.100516;
G4double fA0_max = 1.849792;
G4double fA0_rescaled = fA0 / (fA0_max - fA0_min) - fA0_min/(fA0_max - fA0_min);

G4double fCN2_min = 0.002064164;
G4double fCN2_max = 0.1199827;
G4double fCN2_rescaled = fCN2 / (fCN2_max - fCN2_min) - fCN2_min/(fCN2_max - fCN2_min);

G4double fP1_min = 10.09451;
G4double fP1_max = 99.95741;
G4double fP1_rescaled = fP1 / (fP1_max - fP1_min) - fP1_min/(fP1_max - fP1_min);

G4cout << "Xof rescaled = " << fXof_rescaled << G4endl;
G4cout << "A0 rescaled = " << fA0_rescaled << G4endl;
G4cout << "CN2 rescaled = " << fCN2_rescaled << G4endl;
G4cout << "P1 rescaled = " << fP1_rescaled << G4endl;

std::vector<G4double> input_tensor_values =
  {fXof_rescaled, fA0_rescaled, fCN2_rescaled, fP1_rescaled};

```

```

/gun/SetStatusONNX true
/laser/SetOffsetLaserFocus 1680 ## um
/laser/SetNormVecPotential 1.23
/laser/SetFracDopTargetChamber 0.0617 # %(/100)
/laser/SetPressure 47.8 #mbar

```

From real values, each parameter is rescaled according to min/max transformation

```

// kinetic energy
G4double Ekin_min = 58.49625*MeV;
G4double Ekin_max = 725.2073*MeV;
G4double Ekin = out_vals[0] * (Ekin_max - Ekin_min) + Ekin_min;
G4cout << "Ekin = " << Ekin << G4endl;

// spread of kinetic energy
G4double dEkin_min = 0.000826999;
G4double dEkin_max = 0.7512749;
G4double dEkin = out_vals[1] * (dEkin_max - dEkin_min) + dEkin_min;
G4cout << "dEkin = " << dEkin << G4endl;

G4double Q_min = 6.50e-17;
G4double Q_max = 9.69e-10;
G4double Q = out_vals[2] * (Q_max - Q_min) + Q_min;
G4cout << "Q = " << Q << G4endl;

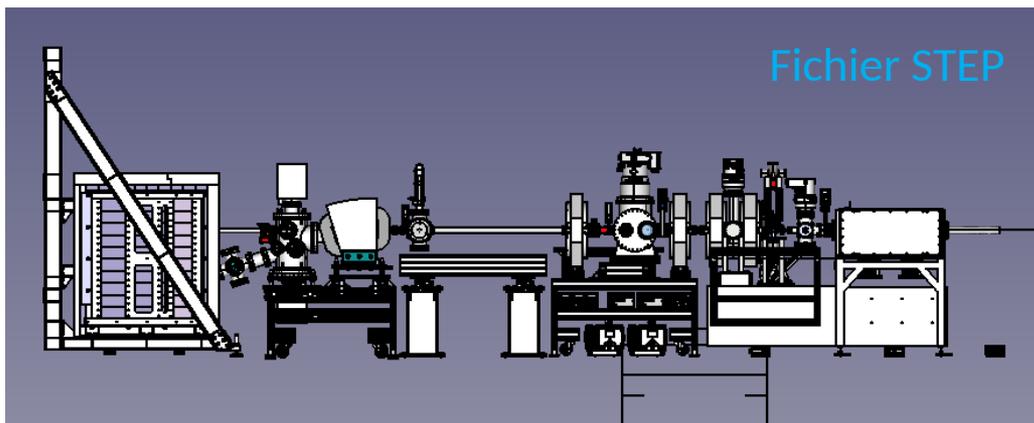
// beam emittance (by now it's the same for x and y)
G4double epsb_min = 2.50e-9 ;
G4double epsb_max = 8.08e-5 ;
G4double epsb = out_vals[3] * (epsb_max - epsb_min) + epsb_min;
G4cout << "beam emittance = " << epsb << G4endl;

// gaussian with Ekin mean and dEkin standard deviation
Ekin = G4RandGauss::shoot(Ekin, dEkin*Ekin);
G4cout << "Ekin from random shoot = " << Ekin << G4endl;

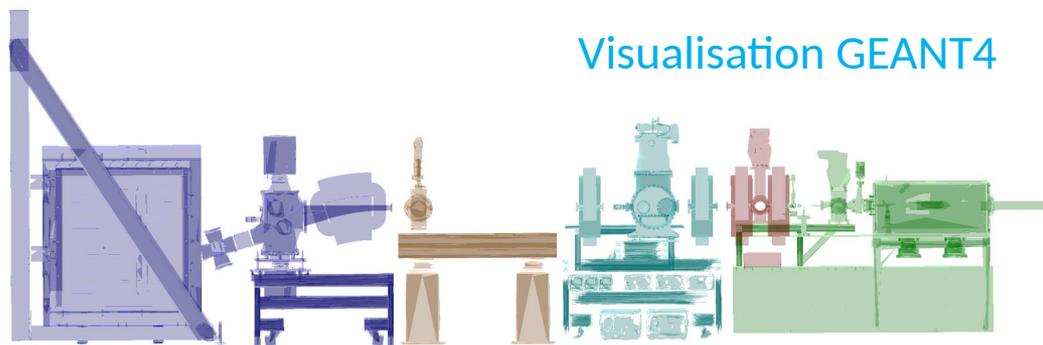
```

Modelization on GEANT4 :

- Modelization of PALLAS [via STEP files]



Conversion from STEP
files into GDML using
FreeCAD software



Modelization on Geant4 :

- Modelization of PALLAS [via STEP files]
- Implementation MultiThreading
- Implementation collimators for studies
- Implementation documentation



huber@cenbg.in2p3.f

Simulation available on
personal GitHub :

https://github.com/ahuber33/PALLAS_Collimateurs_Simulation/tree/main



Simulation also available on
official GitLab PALLAS :

[https://gitlab.in2p3.fr/pallas/design/-/tree/main?
ref_type=heads](https://gitlab.in2p3.fr/pallas/design/-/tree/main?ref_type=heads)



```
PALLAS_Collimateurs_Simulation / README.md
Preview Code Blame 232 lines (187 loc) · 11.9 KB Code 55% faster with GitHub Copilot Raw [copy] [download] [edit]

INSTRUCTIONS TO USE THE SIMULATION

• Download the VMWare Geant4.11.2.1

git clone https://github.com/ahuber33/PALLAS_Collimateurs_Simulation

• Go to build Folder and use this command :

cmake -DGeant4_DIR=$G4COMP ../
make -j4

then compile it with make

• The executable PALLAS_CollSim will be add to your bin folder
• If you want to have a visualization, launch this command :

./PALLAS_CollSim [name of ROOT file ]

It will generate x particle according to the vis.mac with QT and you will have a ROOT file with the name you gave located in the Resultats folder.

• If you want to have statistics without the visualization, use this command :

./PALLAS_CollSim [name of ROOT file] [number of events generated] [number of threads] [name of macro]
```

Modelization on Geant4 :

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```
/control/alias VerticalCollimatorThickness 20
/control/alias HorizontalCollimatorThickness 60
/control/alias CollimatorSpectrometerDistance 50
/control/alias CollimatorVHDistance 10
/control/alias YParticleGenerationOffset 140 #Sum of precedent values
```

```
#####
##### PART FOR MESSENGER INFORMATIONS #####
#####
```

```
/geometry/SetStatusRoundCollimator false
/geometry/SetCollimatorThickness 150 mm
/geometry/SetCollimatorInternalRadius 10 mm
/geometry/SetCollimatorExternalRadius 100 mm
/geometry/SetCollimatorDistanceBetweenPlates 0 mm

/geometry/SetVerticalCollimatorMaterial G4_W
/geometry/SetHorizontalCollimatorMaterial G4_Pb

/geometry/SetVerticalCollimatorThickness {VerticalCollimatorThickness} mm
/geometry/SetHorizontalCollimatorThickness {HorizontalCollimatorThickness} mm
/geometry/SetCollimatorSpectrometerDistance {CollimatorSpectrometerDistance} mm
/geometry/SetCollimatorVHDistance {CollimatorVHDistance} mm
/gun/SetYParticleGenerationOffset {YParticleGenerationOffset} mm
/geometry/SetOpenVerticalCollimator 0 mm
/geometry/SetOpenHorizontalCollimator 0 mm
/geometry/SetCollimatorLength 100 mm
```

```
/display/SetStatusDisplayCelluleGeometry false
/display/SetStatusDisplayLIFGeometry false
/display/SetStatusDisplaySection1Geometry false
/display/SetStatusDisplaySection2Geometry false
/display/SetStatusDisplaySection3Geometry false
/display/SetStatusDisplaySection4Geometry true
/display/SetStatusDisplaySection4DumpGeometry false
/run/reinitializeGeometry
```

```
/field/SetStatusMapBField false
/field/SetConstantBField 0.0 tesla #0.4 tesla
```

```
/step/SetTrackingStatus false
```

• /geometry/ corresponds to definition of specific volume & distance (here the Collimator) :

- SetStatusRoundCollimator for the status of if we use Round collimator or not (USED FOR TESTS)
- SetCollimatorThickness for the thickness of the collimator
- SetCollimatorInternalRadius for the part of the collimator without matter
- SetCollimatorExternalRadius for the external radius of the collimator
- SetVerticalCollimatorMaterial to define the material of the vertical collimator
- SetHorizontalCollimatorMaterial to define the material of the horizontal collimator
- SetVerticalCollimatorThickness to define the thickness of the vertical collimator from the alias defined before
- SetHorizontalCollimatorThickness to define the thickness of the horizontal collimator from the alias defined before
- SetCollimatorSpectrometerDistance to define the distance between the end of the collimator and the begin of spectrometer from the alias defined before
- SetCollimatorVHDistance define the distance between the end of the vertical collimator and the begin of the horizontal collimator from the alias defined before
- SetYParticleGenerationOffset define the Offset parameter for the apticle generation according to the different values of the 2 collimators. => DEFINED WITH GUN MESSENGER
- SetOpenVerticalCollimator define the aperture of the vertical collimator
- SetOpenHorizontalCollimator define the aperture of the horizontal collimator
- SetCollimatorLength define the other dimensions of the collimator
- IMPORTANT You can find a Geometry.cc file where all the possible LogicalVolume are created and a PALLAS_CollSimGeometryConstruction.cc where these functions are call to construct the geometry.

• /display/ manages if some part of the geometry are taken into account or no :

- SetStatusDisplayCelluleGeometry for the "2 cells part"
- SetStatusDisplayLIFGeometry for the LIF part
- SetStatusDisplaySection1Geometry for the 2 first Quadrupole with ISOChamber
- SetStatusDisplaySection2Geometry for Q3, Q4, ASMRemovalChamber, BreadboardRemovalChamber, ChassisRemovalChamber and ISOTubes
- SetStatusDisplaySection3Geometry for ASMPoutre & YAGStation
- SetStatusDisplaySection4Geometry for DipoleChamber, Dipole & 2 YAGs
- SetStatusDisplaySection4DumpGeometry for shieldings, chassis & DiagsChamber
- /run/reinitializeGeometry is mandatory to take into account the messegner informations

• /field/ manages the magnetic field inside the spectrometer :

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- Modelization of PALLAS [via STEP files]
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-
- *ML model for particles generation*
[collaboration with IJCLab & INFN]
 - **ML model by IJCLab**
 - **ML implementation in Geant4 using ONNX by INFN**
-
- **Implementation of tracking in optics (quad)**
 - **Submission of the example into Geant4**
 - **Development of more complex neural network models (GP-based surrogate model, ...)**





Thank you for attention!